Triggering Rogue Waves in Opposing Currents

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We show that rogue waves can be triggered naturally when a stable wave train enters a region of an opposing current flow. We demonstrate that the maximum amplitude of the rogue wave depends on the ratio between the current velocity U_0 and the wave group velocity c_g . We also reveal that an opposing current can force the development of rogue waves in random wave fields, resulting in a substantial change of the statistical properties of the surface elevation. The present results can be directly adopted in any field of physics in which the focusing nonlinear Schrödinger equation with nonconstant coefficient is applicable. In particular, nonlinear optics laboratory experiments are natural candidates for verifying experimentally our results.

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In the ocean, rogue waves are often observed in regions characterized by strong currents like the Gulf Stream, the Agulhas Current, and the Kuroshio Current [1,2]. Several ship accidents have been reported in these regions as being due to the impact with very large waves. One of these occurred in February 1986 to the SS Spray, which was traveling along the East Coast of the United States. The ship was hit by a wave with a height of approximately 17 m (estimated by eyes from the deck of the ship), which was the second of a system of three consecutive large waves, commonly known as the three sisters. This particular wave system is usually observed in the nonlinear stages of the modulational instability process. Such instability was discovered in the late 1960s independently by Zakharov [3] and Benjamin and Feir [4] (an interesting and stimulating review on the subject can be found in [5]). The theory is based on the linear stability analysis of a plane wave and predicts that a small perturbation may grow exponentially when $\varepsilon N >$ $1/\sqrt{2}$, where $\varepsilon = k_0 A_0$ is the steepness of the plane wave, with k_0 its wave number and A_0 its amplitude; $N = \omega_0 / \Delta \Omega$ is the number of waves under the modulation, with ω_0 the angular frequency corresponding to the wave number k_0 and $\Delta \Omega$ the angular frequency of the modulation.

The nonlinear stages of the modulational instability are described by the exact breather solutions of the nonlinear Schrödinger (NLS) equation [6–8]. Breathers are coherent structures that oscillate in space or time and have the peculiarity of changing their amplitudes as they propagate. They can grow up to a maximum of 3 times their initial amplitude and have been considered in various fields of physics as a plausible object that describes the formation

of rogue waves [9,10]. Such solutions have also been observed in fully nonlinear simulations of the Euler equation [11]. Breather solutions may also exist embedded in random waves [12] and can affect the probability density function of the surface elevation and wave height distribution [13,14]. We mention here that the concept of rogue waves is rapidly expanding to other disciplines such as nonlinear optics and condensed matter (see, for example, [15–20]).

In general, ocean waves are characterized by a small value of εN . Wind seas, which are waves forced by the local wind field, have moderately large steepness but the spectral bandwidth only rarely allows for a large number of the product εN that satisfies the instability criterion. On the other hand, swells, i.e., long crested waves that have moved out of the generating region, are characterized by a narrow spectrum (i.e., large N) in both angle and frequency, but they are not particularly steep. Hence, breathers (rogue waves) are fortunately rare objects in the ocean. However, if swells enter into a current, their properties can change, and, as we will show in this Letter, breather solutions can be naturally triggered.

Our analysis is based on the computation of a modified nonlinear Schroedinger equation, recently derived in Ref. [21], that accounts for a current, U = U(x), assumed to be small with respect to the wave phase velocity c_p : $U/c_p = O(\varepsilon)$. The derivation requires also that the current is a slowly varying function of the spatial coordinate, i.e., $1/(\Lambda k_0) = O(\varepsilon)$, with Λ the entry length of the current (typical space scale over which the current changes). The equation describes the evolution in space of the wave envelope A = A(x, t). In dimensional variables it takes the following form:

$$\begin{bmatrix} \frac{\partial A}{\partial x} + \frac{1}{c_g} \left(1 - \frac{3}{2} \frac{U}{c_g} \right) \frac{\partial A}{\partial t} \end{bmatrix} + i \frac{k_0}{\sigma_0^2} \frac{\partial^2 A}{\partial t^2} + i k_0^3 |A|^2 A$$
$$= -\frac{1}{2c_g} \frac{dU}{dx} A - i k_0 \frac{U}{c_g} \left(1 - \frac{5}{4} \frac{U}{c_g} \right) A, \tag{1}$$

with c_g the group velocity, k_0 the wave number of the carrier wave, and $\sigma_0 = \sqrt{gk_0}$, with g the gravity acceleration. We have found that Eq. (1) can be reduced to the standard NLS equation with variable coefficients by applying the following transformations:

$$A = B \exp\left[-\int_{0}^{x} i k_{0} \frac{U}{c_{g}} \left(1 - \frac{5}{4} \frac{U}{c_{g}}\right) - \frac{1}{2c_{g}} \frac{dU}{dX} dX\right], \quad (2)$$

$$x' = x, \qquad t' = t - \int_0^x \frac{1}{V(X)} dX,$$
 (3)

after which Eq. (1) assumes the form

$$\frac{\partial B}{\partial x} + i \frac{k_0}{\sigma_0^2} \frac{\partial^2 B}{\partial t^2} + i\beta(x)|B|^2 B = 0, \tag{4}$$

where

$$\frac{1}{V(x)} = \frac{1}{c_g} \left(1 - \frac{3}{2} \frac{U}{c_g} \right), \qquad \beta(x) = k_0^3 \exp\left[-\frac{\Delta U}{c_g} \right], \quad (5)$$

with $\Delta U(x) = U(x) - U(0)$; primes have been omitted for brevity. Equation (1) does not preserve the energy, which can be shown to change in space as follows: $E(x) = \int |A|^2 dt = \exp[-\Delta U/c_g] \int |B|^2 dt$. As the waves enter into a current, their wave height increases if $\Delta U < 0$ (opposing current) and decrease if $\Delta U > 0$ (copropagating current).

In the absence of a current, U = 0, Eq. (1) admit breather solutions [6], whose maximum amplitude reached during the evolution of the wave group is

$$\frac{A_{\max}}{A_0} = 1 + 2\sqrt{1 - \left(\frac{1}{\sqrt{2\varepsilon N}}\right)^2}.$$
 (6)

For $\varepsilon N < 1/\sqrt{2}$, wave groups are stable; for $\varepsilon N > 1/\sqrt{2}$, the amplification factor reaches the maximum value of three, which corresponds to the Peregrine soliton, observed experimentally recently in nonlinear optical fibers [16].

We will consider the evolution of a wave train initially in a region of zero current propagating into a stationary current characterized by an entry length Λ . We have used in our computation the following simple mathematical expression for the current:

$$U(x) = \begin{cases} 0 & \text{if } x < x_0, \\ U_0 \sin^2 \left[\frac{\pi}{2\Lambda} (x - x_0) \right] & \text{if } x_0 \le x < x_0 + \Lambda, \\ U_0 & \text{if } x \ge x_0 + \Lambda. \end{cases}$$
(7)

Here *x* is the coordinate along which the waves propagate, and U_0 is the asymptotic value (large x) of the current that can be either positive or negative for copropagating or opposing currents, respectively. For such a current field, we show a first example of the formation of a rogue wave in an opposing current in Fig. 1. As initial conditions for our numerical experiments, we have considered a perturbed plane wave with $\varepsilon = 0.1$ and N = 7 (in terms of dimensional quantities, we can think of a wave characterized by a frequency $f_0 = 0.1$ Hz and amplitude 2.5 m, perturbed by a frequency $\Delta f = f_0/N \simeq 0.014$ Hz). In the absence of current, the wave train is stable and no modulational instability is observed. After 60 wavelengths of propagation, the wave group enters into a current characterized by $U_0/c_g = -0.2$ (opposing current) and $\Lambda = 10\lambda$. At $x/\lambda = 60$ the whole envelope grows in amplitude because the energy $E(x) = \int |A(x, t)|^2 dt$ changes, in the presence of a current gradient. Subsequently, the envelope starts being strongly modulated, reaching approximately 2 times its local standard deviation $\sqrt{E(x)}$. The plot shows a clear example of formation of a rogue wave starting from a stable plane wave. Such rogue wave is of the Akhmediev type [6], i.e., is periodic in time (three periods are shown in the figure), which is different from the Peregrine type [16] of solution, which oscillates only once in space and time. We have performed a systematic study on the dependence of the maximum amplitude [divided by $\sqrt{E(x)}$] reached by the envelope as a function of the ratio U_0/c_g , which was varied from 0.1 to 0.4 (stronger current may result in wave blocking phenomena and wave breaking). The results are shown in Fig. 2, where the dots correspond to our numerical results. The plot indicates that the normalized maximum amplitude increases with increasing $|U_0|$, evidencing that the originally stable plane wave has been transformed into a breather in the presence of a current. In the figure, we



FIG. 1 (color). Evolution in space and in time, normalized by the wave length and period, respectively, of the wave envelope. The wave propagates for 60 wavelengths before entering into the opposing current of velocity $U_0 = -0.25c_g$.



FIG. 2. The normalized maximum amplitude as a function of U_0/c_g . The dots are the results from the numerical simulations, and the solid line corresponds to Eq. (8).

also include as a solid line the heuristic prediction based on the following equation:

$$\frac{A_{\max}}{\sqrt{E(x_0 + \Lambda)}} = 1 + 2\sqrt{1 - \left(\frac{\exp[U_0/(2c_g)]}{\sqrt{2\varepsilon}N}\right)^2}.$$
 (8)

Equation (8) is a modification of the exact relation (6). The rationale behind this prediction is that the coefficient in front of the nonlinear term in Eq. (4), once written in nondimensional form, is the same as the one without current except for the exponential factor [see the coefficient $\beta(x)$ in (5)]. As shown in Fig. 2, the numerical results are in excellent agreement with the prediction.

Once the possibility is established that an opposing current may trigger unstable modes, it is of interest to understand whether the statistical properties of the surface elevation and, in particular, the occurrence of extreme events change as random wave trains propagate into the current. We concentrate our analysis on the kurtosis κ , i.e., the fourth-order moment of the probability density function of the surface elevation estimated as $\kappa = \langle \eta^4 \rangle / \langle \eta^2 \rangle^2$, where $\langle \ldots \rangle$ stands for the ensemble average. In the presence of a current, an analytical estimation of the kurtosis is a rather difficult task because of the nonlinearity of the problem. Therefore, we perform direct numerical simulations of the modified NLS equation with initial conditions characterized by the following bell-shape spectrum for the envelope *A*:

$$P(\omega) = \frac{E}{\Delta\Omega\sqrt{2\pi}} \exp\left[-\frac{\omega^2}{2\Delta\Omega^2}\right]$$
(9)

with $\Delta\Omega$ the standard deviation (the width of the spectrum). The phases are considered randomly distributed in [0, 2π). Numerical simulations are computed on a grid of 1024 points, and 600 realizations have been performed. The wave steepness $\sqrt{2}k_0\sqrt{E}$ was selected equal to 0.15, and $\Delta\Omega/\sigma_0 = 0.2$. The kurtosis is therefore estimated first

as a time average, and then the resulting value is averaged over the ensemble. The current is characterized by $x_0 = 0$ and $\Lambda = 10\lambda$, and different values of U_0/c_g are considered. In Fig. 3, the kurtosis is presented as a function of x/λ . The figure clearly indicates a dependence of the kurtosis on the ratio between the current increment and the wave group velocity. This result is to some extent consistent with recent laboratory experiments, which investigated the evolution of mechanically generated, random wave fields over a partially opposing current [22]. In the absence of a current, as shown in Ref. [23], the kurtosis depends on the square of the Benjamin-Feir index (BFI):

$$BFI = \frac{\sqrt{E}k_0}{\Delta\Omega/\sigma_0},$$
 (10)

which is the ratio between the nonlinear and the linear coefficients in the NLS equation properly written in nondimensional form; see [12]. In the presence of the current, we assume the following dependence on the current velocity:

$$\kappa = 3 + a \frac{\pi}{\sqrt{3}} \text{BFI}^2 \exp\left[-b \frac{U_0}{c_g}\right], \qquad (11)$$

where *a* and *b* can be determined *a posteriori* from the numerical simulations. For a = 1 and b = 1, the kurtosis estimated through (11) corresponds to an analytical result that can be obtained by a quasi-Gaussian approximation under the hypothesis that the wave spectrum and the current field are slowly varying in space. The derivation follows the one presented in Ref. [23] performed in the absence of current. We mention here that our aim is not to establish quantitatively the validity of the closure model but to understand how the opposing current influences the statistics of the waves. In order to verify the exponential factor in (11), we first compute from the initial conditions the BFI, then the asymptotic



FIG. 3. Evolution of the kurtosis as a function of the normalized distance x for different simulations corresponding to different values of $\Delta U/c_g$. For larger values of the $\Delta U/c_g$, there is a clear indication of stronger deviations from Gaussian statistics.



FIG. 4. $f(\Delta U/c_g) = \ln[(\kappa - 3)/(a\pi BFI^2/\sqrt{3})]$ as a function of $\Delta U/c_g$. Dots are the results from the numerical computation, and the solid line is obtained by a linear fit.

(large x) value of the kurtosis is measured as an average value of the kurtosis over the last 20 wavelengths (see Fig. 3), and last we determine the coefficient a from the simulation with $\Delta U = 0$ (the resulting value is a =1.133). In Fig. 4, we show the quantity $f(\Delta U/c_g) =$ $\ln[(\kappa - 3)/(aBFI^2\pi/\sqrt{3})]$ as a function of $\Delta U/c_g$. The points from the simulation lie on a straight line which indicates that the assumed exponential dependence is consistent with our numerical simulations. In the figure, we also show the linear fit, where the slope is b = 1.29. Moreover, we consider the exceedance probability [defined as $\int_x^{\infty} p(x') dx'$, with p(x) the probability density function] for the envelope computed at $x = 60\lambda$ for the case of $\Delta U/c_g = 0$ and $\Delta U/c_g = -0.4$. The probability of occurrence of rogue waves increases notably as the opposing current is stronger. Results are presented in Fig. 5, where we have also plotted the exceedance



FIG. 5. The probability of exceedance for $|A|/\sqrt{2E}$ for the case of a linear system (dashed line), a nonlinear system without current (solid line), and a nonlinear system in the presence of an opposing current (dotted line).

probability for Rayleigh distribution which is the one estimated for a linear process. In Ref. [24], the appearance of rogue waves in an NLS equation with third-order dispersion has been discussed in terms of the ratio between the nonlinear and linear parts of the Hamiltonian. In our case such a ratio, proportional to the BFI, calculated for the initial condition is equal to 0.3; our simulations are in the intermittentlike rogue wave regime—they appear and disappear erratically.

Ocean swells are, in general, not very steep, and wave packets are stable in terms of modulational instability. However, we have shown that breathers may be triggered when swells enter into a region of opposing current. This is an important result that should be kept in mind when ships navigate in the Gulf Stream or in the Agulhas Current or Kuroshio Current in the presence of opposing waves. Indeed, such currents may reach velocities up to 1.5 m per second, and for a group velocity corresponding to waves of period equal to 10 s (a typical condition during storms), the ratio $\Delta U/c_g$ is of the order of 0.2, large enough to trigger a dangerous rogue wave. We underline that this is a completely different process from the development of a caustic, a pure linear mechanism [25–27]. From a physical point of view, the mechanism of formation of rogue waves can be summarized as follows: An initial wave whose perturbation is stable in terms of the modulational instability may become unstable in the presence of a current because of a shift of the modulational instability band. The instability triggers the formation of a breather. Note that this mechanism is particularly effective if the initial wave is characterized by an amplitude and a wave number such that the perturbation frequency lies just outside the instability region (see, e.g., Fig. 3.4 in Ref. [28]).

The results presented in this Letter, even though presented in the oceanographic context, may also apply to nonlinear optics physics where the nonlinearity is provided by the type of the material. As shown in Eq. (4), the effect of the current is to change the coefficient of the nonlinear term in the NLS equation. New experiments characterized by materials that change their nonlinear properties in space could be easily performed, and the predictions of the present work could be verified.

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